



## COURSE DESCRIPTION CARD - SYLLABUS

Course name

Machine vision

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### Course

Field of study

Mechatronics

Area of study (specialization)

Level of study

Second-cycle studies

Form of study

full-time

Year/Semester

1/2

Profile of study

general academic

Course offered in

Polish

Requirements

compulsory

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### Number of hours

Lecture

15

Tutorials

Laboratory classes

15

Projects/seminars

0

Other (e.g. online)

### Number of credit points

2

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### Lecturers

Responsible for the course/lecturer:

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Wydział Inżynierii Mechanicznej

ul. Piotrowo 3, 60-965 Poznań

Responsible for the course/lecturer:

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### Prerequisites

The student should have basic knowledge in the field of automation, optics, robotics, elements of



automation, drivers and programming. He should also have the ability to obtain information from the indicated sources and be ready to cooperate as part of the team..

### Course objective

The student's acquisition of design and configuration skills. software and implementation of selected elements of machine vision systems.

Developing students' skills of practical implementation of machine vision solutions into practice.

### Course-related learning outcomes

#### Knowledge

1. Knowledge of the principles of operation of machine vision systems.
2. Knowledge of how to develop and design the connectivity of the device with supervisory systems, eg PLC or PC.
3. Knowledge of how to set the optics on the camera.
4. Knowledge of what elements of the system to choose for a given task.
5. Knowledge of the basics of optics.

#### Skills

1. Is able to design and program a vision system
2. Can select elements, including the controller, and design simple vision systems
3. Can select the elements of the vision system to work on the production line
4. Is able to program the exchange of camera data with the supervisory system
5. Can use the vision system in practice

#### Social competences

1. Understands the need for lifelong learning; can inspire and organize the learning process of others
2. Can define priorities for the implementation of a specific task
3. Can interact and work in a group
4. Can think and act in an entrepreneurial manner
5. Is aware of the responsibility for his own work and readiness to submit to the principles of teamwork and responsibility for jointly performed tasks

### Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

Laboratory: Credit based on the correct implementation of exercises and reports on each of them



laboratory exercises according to the instructions of the laboratory teacher. Before the exercise short entry checks.

Credit for the lecture on the basis of a written test

### Programme content

Lecture:

1. History of vision systems
2. Examples of vision systems
3. Construction of vision systems
4. OpenCV library
5. OCR - text recognition in vision systems
6. Detection of shapes in vision systems
- 7 Calibration, calculations, filters in vision systems

Lab:

1. OpenCV - the basics of using the library
2. Detection of lines and shapes
3. Face detection
4. OCR and Aruco library
5. Filtration in vision systems
6. Pattern recognition
7. Measurements of sizes and calculation of dimensions

### Teaching methods

Lecture: multimedia presentation and software application demonstration

Laboratory: Exercises performed by students in groups under the supervision of the teacher.

### Bibliography

Basic

1. Jähne B., Digital Image Processing, Springer, 2005, 6th revised and extended edition
2. Siciliano B., Khatib O., Springer Handbook of Robotics, Springer, 2008, 1st Edition



Additional

1. Sankowski D., Morosov W., Strzecha K., Przetwarzanie i analiza obrazów w systemach przemysłowych, PWN, Warszawa, 2011

**Breakdown of average student's workload**

	Hours	ECTS
Total workload	50	2,0
Classes requiring direct contact with the teacher	30	1,0
Student's own work (literature studies, preparation for laboratory classes/tutorials, preparation for tests/exam, project preparation) <sup>1</sup>	20	1,0

<sup>1</sup> delete or add other activities as appropriate